

MMQ™ VG

Applications

The MMQ™ VG has a wide variety of applications.

- Antenna Pointing
- Targets and drones
- EO/IR Stabilization
- Unmanned Aerial Vehicles
- Remotely Operated Vehicles (Underwater)
- General Aviation (Experimental)
- Agriculture (Smart Farming)
- Robotics
- Automotive Testing



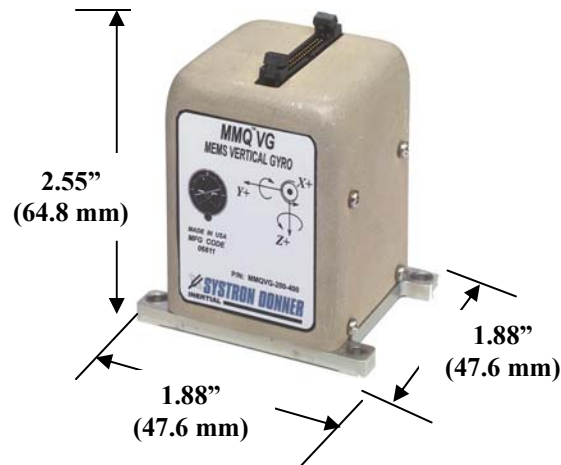
Description

The MMQ™ VG offers a unique combination of the Systron Donner Inertial solid-state MMQ50 Inertial Measurement Unit (IMU) and advanced software that calculates a Vertical Gyro (VG) solution from the gyro and accelerometer sensors. The MMQVG's MEMS quartz rate sensors and MEMS accelerometers make up an IMU system that is used to calculate a highly accurate Roll and Pitch angle solution in varying dynamic applications. The user can configure the MMQVG to output data at various sample rates with extremely low output rate jitter, and the data output format is simple to understand containing the 6 sensor outputs, the angle outputs, a Built-In-Test (BIT) word output and a multi-parameter revolving word output that provides system information including version string. The MMQVG combines tremendous performance and versatility with an extremely compact size, low power consumption and low weight.



Key Performance Features

- Extremely Small Size
- Vertical Gyro Solution for many Dynamic Applications
- RS-232 Digital Interface
- Low Power Consumption (<5W)
- Configurable Output Rate
- Jitter Free Output Rate (400 Hz Max)
- Tested to meet TSO-C4c bank (roll) and pitch angle performance
- MMQVG Demo Software supplied to facilitate integration



| Physical Characteristics | |
|--|---|
| Part Number | MMQVG-200-400 |
| Size (Vol.) | 9.0 in ³ (1.88"W x 1.88"D x 2.55"H) (48 mm x 48 mm x 65 mm) |
| Weight | <0.50 lbs (<0.227 kg) |
| Power | + and - 12 Vdc at < 5 watts total |
| I/O | RS-232 - 400 Hz Output Rate with < 100 microsecond jitter |
| Attitude Performance | |
| Static Accuracy (Roll/Pitch) | < 0.5 Deg |
| Dynamic Accuracy (Roll/Pitch) | 1.5 Deg RMS - Tested to TSO-C4c bank and pitch performance standards |
| Rate Channels | |
| Range | ±200°/sec |
| Bias Turn-on to turn-on Stability | ≤100°/hr, 1 σ |
| Bias In-run Stability (at any temperature) | 100°/hr, 1 σ |
| Bias Instability | <4-15°/hr |
| Angle Random Walk | 0.3 °/rt-hr (0.005 °sec/rt-Hz) |
| Scale Factor error | ≤5000 ppm (0.5%) |
| Alignment | ≤5 mrad |
| Bandwidth (-90°) | 50 Hz, nominal |
| Acceleration Channels | |
| Range | ± 10g |
| Bias Turn-on to turn-on Stability | ≤2.5 mg, 1σ |
| Bias In-run Stability (at any temperature) | ≤3 mg, 1 σ |
| Velocity Random Walk | 0.5 mg/rt-Hz |
| Scale Factor Error | ≤5000 ppm (0.5%) |
| Alignment | ≤5 mrad |
| Bandwidth (-90°) | 50 Hz, nominal |
| Environmental | |
| Temperature Range | -54°C to +70°C (operating) |
| Vibration, random | 6.0g rms, 20Hz -2kHz, flat Meets DO-160D Curves C, C1 |
| Shock, operating | 30g, powered Meets DO-160D operational shock and crash safety |
| Altitude | 35,000 ft. Meets DO-160D Category C |

For more information contact:

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